

Solutions HW #2

Problem 1:

$$(1) \underline{a} \times (\underline{b} \times \underline{c}) = (\underline{a} \cdot \underline{c}) \underline{b} - (\underline{a} \cdot \underline{b}) \underline{c}$$

$$\text{let } \underline{a} = a_i \underline{e}_i, \underline{b} = b_j \underline{e}_j, \underline{c} = c_k \underline{e}_k$$

$$\begin{aligned} \underline{a} \times (\underline{b} \times \underline{c}) &= \underline{a} \times (\epsilon_{jkl} b_j c_k \underline{e}_l) \\ &= \underbrace{\epsilon_{ilm} \epsilon_{jkl}} a_i b_j c_k \underline{e}_m \\ &= (\delta_{mj} \delta_{il} - \delta_{ml} \delta_{ij}) a_i b_j c_k \underline{e}_m \\ &= a_k c_k b_m \underline{e}_m - a_i b_i c_m \underline{e}_m \\ &= (\underline{a} \cdot \underline{c}) \underline{b} - (\underline{a} \cdot \underline{b}) \underline{c} \end{aligned}$$

$$(2) \underline{a} \cdot (\underline{b} \times \underline{c}) = \underline{b} \cdot (\underline{c} \times \underline{a})$$

$$\begin{aligned} \underline{a} \cdot (\underline{b} \times \underline{c}) &= a_i \underline{e}_i \cdot (\epsilon_{jkl} b_j c_k \underline{e}_l) \\ &= a_i b_j c_k \epsilon_{jkl} \delta_{il} = \underline{a_i b_j c_k \epsilon_{jki}} \end{aligned}$$

$$\begin{aligned} \underline{b} \cdot (\underline{c} \times \underline{a}) &= b_j \underline{e}_j \cdot (\epsilon_{kic} c_k a_i \underline{e}_l) \\ &= a_i b_j c_k \epsilon_{kic} \delta_{jl} = \underline{a_i b_j c_k \epsilon_{kij}} \end{aligned}$$

$$\text{since } \epsilon_{jki} = \epsilon_{kij} \Rightarrow \underline{a} \cdot (\underline{b} \times \underline{c}) = \underline{b} \cdot (\underline{c} \times \underline{a})$$

Problem 2:

$$(1) \text{ show that } \nabla \cdot (\nabla \times \underline{v}) = 0 \quad \nabla = \frac{\partial}{\partial x_m} \underline{e}_m$$

$$\Rightarrow \nabla \cdot (\nabla \times \underline{v}) = \frac{\partial}{\partial x_i} \underline{e}_i \cdot \left(\frac{\partial}{\partial x_j} \underline{e}_j \times v_k \underline{e}_k \right)$$

$$= \frac{\partial^2 v_k}{\partial x_i \partial x_j} \underline{e}_i \cdot \epsilon_{jkl} \underline{e}_l = \frac{\partial^2 v_k}{\partial x_i \partial x_j} \underbrace{\epsilon_{jkl} \delta_{il}}_{\epsilon_{jki} = \epsilon_{ijk}}$$

$$\begin{aligned} &= \epsilon_{ijk} \frac{\partial^2 v_k}{\partial x_i \partial x_j} = \frac{\partial^2 v_3}{\partial x_1 \partial x_2} + \frac{\partial^2 v_1}{\partial x_2 \partial x_3} + \frac{\partial^2 v_2}{\partial x_3 \partial x_1} \\ &\quad - \frac{\partial^2 v_3}{\partial x_2 \partial x_1} - \frac{\partial^2 v_1}{\partial x_3 \partial x_2} - \frac{\partial^2 v_2}{\partial x_1 \partial x_3} = 0 \end{aligned}$$

$$(2) \nabla \cdot (\nabla \phi) = \nabla^2 \phi$$

$$\begin{aligned} \nabla \cdot (\nabla \phi) &= \frac{\partial}{\partial x_i} \underline{e}_i \cdot \left(\frac{\partial \phi}{\partial x_j} \underline{e}_j \right) = \frac{\partial^2 \phi}{\partial x_i \partial x_j} \delta_{ij} \\ &= \frac{\partial^2 \phi}{\partial x_i \partial x_i} = \nabla^2 \phi \end{aligned}$$

Problem 3

$$(1) M_{ij} \delta_{ij} = M_{ii} = M_{11} + M_{22} + M_{33}$$

$$(2) \delta_{ii} = \delta_{11} + \delta_{22} + \delta_{33} = 3$$

$$(3) x_i y_j \delta_{ij} - x_q y_p \delta_{qp} = x_i y_i - x_q y_q = 0$$

(4) makes no sense! Left side of eqn. has 3 free indices while right hand side has only one free index, it is not compatible.

$$(5) (\delta_{ii} \delta_{jj} - \delta_{ij} \delta_{ij}) = (3 \times 3 - \underbrace{\delta_{ii}}_3) = 6$$

Problem 4:

(1) solve the characteristic eqn. to find eigenvalues ($d_1 > d_2 > d_3$)

$$\det(\underline{A} - \lambda \underline{I}) = 0$$

$$\begin{vmatrix} 1-\lambda & 2 & 3 \\ 2 & 4-\lambda & 6 \\ 3 & 6 & 1-\lambda \end{vmatrix} = 0 = \lambda(\lambda+4)(\lambda-10)$$

$$\Rightarrow \boxed{\lambda_1 = 10}, \boxed{\lambda_2 = 0}, \boxed{\lambda_3 = -4}$$

(2) find corresponding principal directions $\underline{v}^1, \underline{v}^2, \underline{v}^3$

for $d_1 = 10$

$$\underline{A} \underline{v}^{(1)} = d_1 \underline{v}^{(1)} \quad (\text{no sum})$$

$$\begin{bmatrix} 1-10 & 2 & 3 \\ 2 & 4-10 & 6 \\ 3 & 6 & 1-10 \end{bmatrix} \begin{bmatrix} v_1^{(1)} \\ v_2^{(1)} \\ v_3^{(1)} \end{bmatrix} = 0$$

$$\begin{bmatrix} -9 & 2 & 3 \\ 2 & -6 & 6 \\ 3 & 6 & -9 \end{bmatrix} \rightarrow \begin{bmatrix} -9 & 2 & 3 \\ 20 & -10 & 0 \\ -24 & 12 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} -9 & 2 & 3 \\ 20 & -10 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\Rightarrow \left. \begin{array}{l} -9v_1 + 2v_2 + 3v_3 = 0 \\ 20v_1 - 10v_2 = 0 \end{array} \right\} \begin{array}{l} \text{there are only 2} \\ \text{independent eqns for} \\ \text{3 unknowns } (v_1, v_2, v_3) \end{array}$$

Choose $v_2 = 1$, then $v_1 = 1/2$

$$\Rightarrow -9 \cdot \frac{1}{2} + 2 \cdot 1 + 3v_3 = 0 \Rightarrow v_3 = 5/6$$

$$v^{(1)} = \begin{bmatrix} 1/2 \\ 1 \\ 5/6 \end{bmatrix} \xrightarrow[\text{normalized}]{\frac{1}{\sqrt{70}}} \begin{bmatrix} 3 \\ 6 \\ 5 \end{bmatrix} \cdot \frac{1}{\sqrt{70}}$$

for $d_2 = 0$

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 1 \end{bmatrix} \begin{bmatrix} v_1^{(2)} \\ v_2^{(2)} \\ v_3^{(2)} \end{bmatrix} = 0$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & -8 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0 \Rightarrow \left. \begin{array}{l} z = 0 \\ x = -2y \end{array} \right\} \begin{array}{l} \text{Choose } y = 1 \\ x = -2 \end{array}$$

$$v^{(2)} = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} \xrightarrow[\text{normalized}]{\frac{1}{\sqrt{5}}} \frac{1}{\sqrt{5}} \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$$

for $d_3 = -4$

$$\begin{bmatrix} 5 & 2 & 3 \\ 2 & 8 & 6 \\ 3 & 6 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 5 & 2 & 3 \\ 0 & 36/5 & 24/5 \\ 0 & 24/5 & 16/5 \end{bmatrix} \rightarrow \begin{bmatrix} 5 & 2 & 3 \\ 0 & 36/5 & 24/5 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$$

$$\text{choose } y = 1 \Rightarrow z = -\frac{3}{2} \Rightarrow x = \frac{1}{2}$$

$$\Rightarrow \underline{v}^{(3)} = \begin{bmatrix} 1/2 \\ 1 \\ -3/2 \end{bmatrix} \xrightarrow[\text{normalized}]{/\sqrt{14}} \frac{1}{\sqrt{14}} \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix}$$

$$\left. \begin{aligned} (2) \quad \underline{v}^{(1)} \cdot \underline{v}^{(2)} &= [1/2 \quad 1 \quad 5/6] \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} = 0 \\ \underline{v}^{(2)} \cdot \underline{v}^{(3)} &= [-2 \quad 1 \quad 0] \begin{bmatrix} 1/2 \\ 1 \\ -3/2 \end{bmatrix} = 0 \\ \underline{v}^{(1)} \cdot \underline{v}^{(3)} &= [1/2 \quad 1 \quad 5/6] \begin{bmatrix} 1/2 \\ 1 \\ -3/2 \end{bmatrix} = 0 \end{aligned} \right\} \Rightarrow \underline{v}^{(1)}, \underline{v}^{(2)}, \underline{v}^{(3)} \text{ are mutually orthogonal!}$$

(4) find the invariants in terms of d_1, d_2, d_3

$$[\underline{A}] = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 1 \end{bmatrix} \xrightarrow[\text{(spectral form)}]{\text{diagonalized}} \begin{bmatrix} 10 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -4 \end{bmatrix}$$

$$I_1 = \text{tr}(\underline{A}) = d_1 + d_2 + d_3 = 10 + 0 - 4 = \underline{6}$$

$$I_2 = \begin{vmatrix} 10 & 0 \\ 0 & 0 \end{vmatrix} + \begin{vmatrix} 0 & 0 \\ 0 & -4 \end{vmatrix} + \begin{vmatrix} 10 & 0 \\ 0 & -4 \end{vmatrix} = \underline{-40}$$

$$I_3 = \det(\underline{A}) = d_1 d_2 d_3 = (10)(0)(-4) = \underline{0}$$

In fact we can also calculate the invariants $\{\underline{e}_1, \underline{e}_2, \underline{e}_3\}$ Cartesian frame

$$I_1 = \text{tr}(\underline{A}) = 1 + 4 + 1 = \underline{6}$$

$$I_2 = \begin{vmatrix} 1 & 2 \\ 2 & 4 \end{vmatrix} + \begin{vmatrix} 4 & 6 \\ 6 & 1 \end{vmatrix} + \begin{vmatrix} 1 & 3 \\ 3 & 1 \end{vmatrix} = 0 + (-32) + (-8) = \underline{-40}$$

$$I_3 = \det(\underline{A}) = 1 \cdot (-32) - 2(-16) + 3(0) = \underline{0}$$

The results (I_1, I_2, I_3) are the same in principal frame as in initial Cartesian frame. Actually, those 3 values hold the same in all frames. That's why they are called "invariants".